

## Features

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- A line drawing of the SOMA RNTL 2022 robot arm. The arm is composed of several interconnected segments. At the base, there is a circular motor or sensor unit with a flange. A long, thin arm extends from this base, passing through a joint. The arm then bends at a right angle, with another joint visible. The end of the arm is a gripper mechanism with two fingers. The drawing is a technical illustration showing the mechanical structure of the robot arm.